

**Assignment 1:**

Consider the following transfer function:

$$H(z) = \frac{-z}{z^2 - 2z + \frac{3}{4}}.$$

- a) Determine the poles and zeros of  $H(z)$ , and plot the pole-zero map

Consider the following regions of convergence:

$$\mathbf{R}_1: |z| > \frac{3}{2}$$

$$\mathbf{R}_2: |z| < \frac{1}{2}$$

$$\mathbf{R}_3: \frac{1}{2} < |z| < \frac{3}{2}$$

- b) Compute the inverse  $\mathcal{Z}$ -transform of  $H(z)$  when the region of convergence is  $\mathbf{R}_1$ .
- c) Compute the inverse  $\mathcal{Z}$ -transform of  $H(z)$  when the region of convergence is  $\mathbf{R}_2$ .
- d) Compute the inverse  $\mathcal{Z}$ -transform of  $H(z)$  when the region of convergence is  $\mathbf{R}_3$ .

**Assignment 2:**

A discrete-time signal  $x$  has the following Fourier transform

$$X(\omega) = \frac{1}{1 - ae^{-j\omega}}, \quad |a| < 1.$$

- a) Give an expression for  $x(n)$ .

Give the Fourier transforms of the following signals

- b)  $x(2n + 1)$   
c)  $(x * x)(n)$   
d)  $x(n) \cos(\frac{\pi}{3}n)$

### Assignment 3:

Consider the continuous-time signal

$$x_a(t) = \begin{cases} e^{-\alpha t} e^{-j2\pi f_0 t}, & t \geq 0 \\ 0, & t < 0 \end{cases}, \quad \alpha > 0.$$

a) Show that

$$X_a(f) = \frac{1}{j2\pi(f + f_0) + \alpha}.$$

b) Sketch the magnitude spectrum of  $X_a$  for  $f_0 = 10$  Hz

The signal  $x_a$  is sampled to obtain the discrete-time signal  $x$ .

- c) Sketch the magnitude spectrum of  $X(f)$ , the Fourier transform of the discrete-time signal  $x$ , for  $f_s = 10, 20$  and  $40$  Hz and explain the results in terms of aliasing effects.
- d) What is the minimum sampling frequency  $f_s$  such that the continuous-time signal  $x_a$  can be perfectly recovered from its samples  $x(n)$ ?

#### Assignment 4:

Consider the transfer function

$$H(z) = \frac{z^2 - 1}{z^2 + \frac{1}{4}},$$

of a causal linear time-invariant system with its direct form-II implementation shown below.

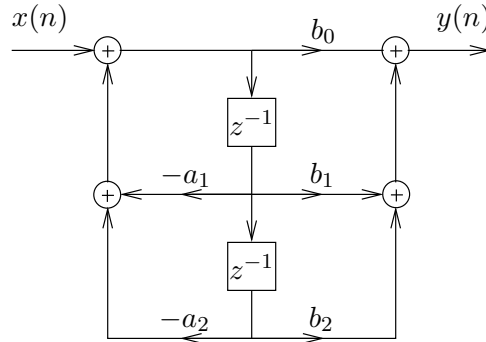


Figure 1: Direct form II implementation of  $H(z)$

- What are the values of the filter coefficients  $b_0, b_1, b_2, a_1$  and  $a_2$ ?
- What can you say about the pole positions and stability of the system? (*Hint: use the stability triangle*)
- What are the zeros and poles of  $H(z)$  and plot the pole-zero map
- Sketch the corresponding magnitude and phase response

Consider the following (suddenly applied) input signal

$$x(n) = (e^{j\frac{\pi}{2}n} + e^{j\pi n}) u(n),$$

and assume the system is initially in rest.

- Compute the steady-state response  $y_{ss}(n)$  when  $x(n)$  is input to the system
- Compute the total response of the system  $y(n) = y_{tr}(n) + y_{ss}(n)$ , where  $y_{tr}(n)$  denotes the transient response of the system