Examination Random Signal Processing (IN4309)

Part I: Digital Signal Processing

November 11, 2011 (14:00 - 17:00)

Important:

Make clear in your answer *how* you reach the final result; the road to the answer is very important (even more important that the answer itself).

Start every assignment on a new sheet. Even in the case you skip one of the exercises, you hand in an empty sheet with the number of the assignment you skipped.

Assignment 1:

Given X(z), the \mathcal{Z} -transform of x(n). Give the inverse \mathcal{Z} -transform of

a)

$$z^k X(z)$$

b)

$$X(-z)$$

c)

$$X(z^{-1})$$

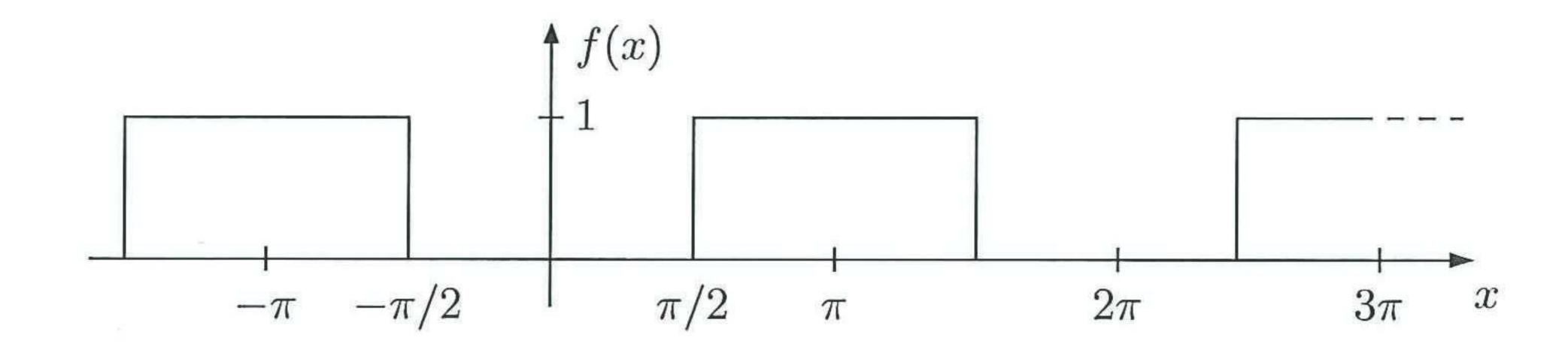


Figure 1: Periodic function.

Assignment 2:

Consider the periodic function f as depicted in Figure 1. A Fourier series representation of f is given by

$$f(x) = a_0 + \sum_{k=1}^{\infty} (a_k \cos(kx) + b_k \sin(kx))$$

- a) Without explicitly computing the coefficients a_k and b_k , what can you say about the values of a_k and b_k ? What is the order of decay of the Fourier coefficients? Motivate your answer.
- b) Compute the a_k and b_k .

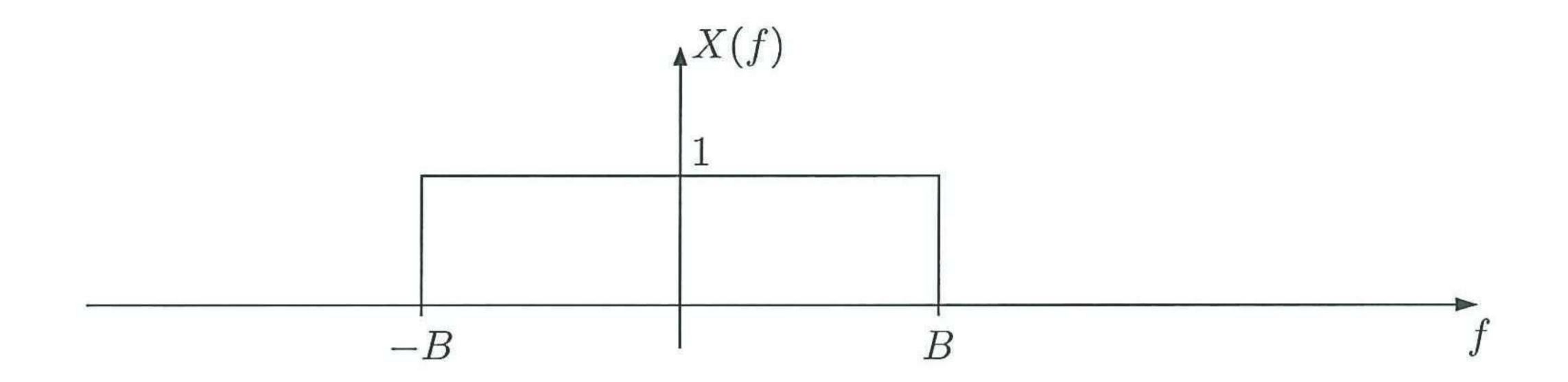


Figure 2: Spectrum X(f).

Assignment 3:

Consider a signal x of which its spectrum is given as depicted in Figure 2.

- a) Is this signal x a discrete-time or continuous-time signal? Motivate your answer.
- b) Is the signal x a periodic or a non-periodic signal? Motivate your answer.

Suppose we sample the signal x(t) with sampling frequency $f_s = 3B$. Afterwards we can reconstruct the (analog) signal out of its samples, say x(n), by a proper interpolation scheme.

- c) What is the relation between x(t) and x(n)?
- d) Sketch the spectrum of x(n).
- e) What is the minimum sampling frequency such that we can perfectly reconstruct x(t) out of its samples x(n) and give the corresponding reconstruction formula.

Assume we want to reconstruct the continuous-time signal using the interpolation function as depicted in Figure 3.

f) How does the continuous-time reconstructed signal look like if we reconstruct using the above mentioned interpolation function?

The reconstruction formula can be expressed in the Fourier domain and is given by

$$\tilde{X}(f) = X(f)G(f),$$

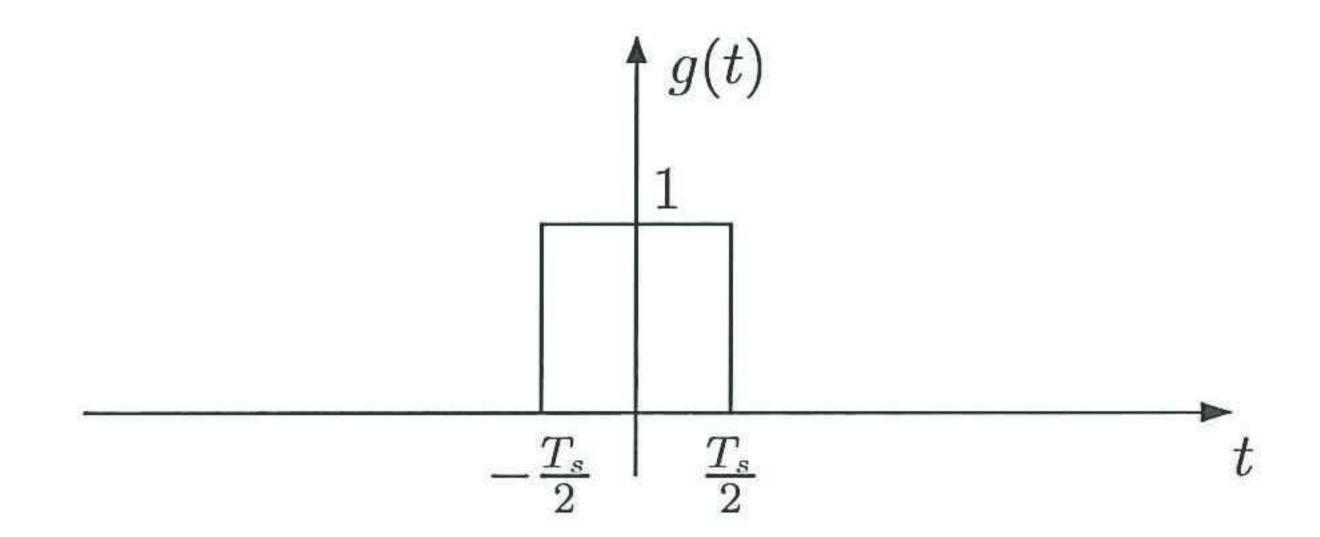


Figure 3: Interpolation function.

where $\tilde{X}(f)$ is the reconstructed signal, X(f) is the spectrum of the discrete-time signal x(n) and G(f) is the Fourier transform of the interpolation function.

- g) Compute G(f).
- h) Sketch the spectrum of $\tilde{X}(f)$
- i) Can we obtain a perfect reconstruction of x(t) by using the interpolation function depicted in Figure 3? Motivate your answer.

Assignment 4:

Consider the following pole-zero map of a causal linear time-invariant system, having zeros at z=0 and $z=r\cos(\theta)$ and poles at $z=re^{j\theta}$ and $z=e^{-j\theta}$.

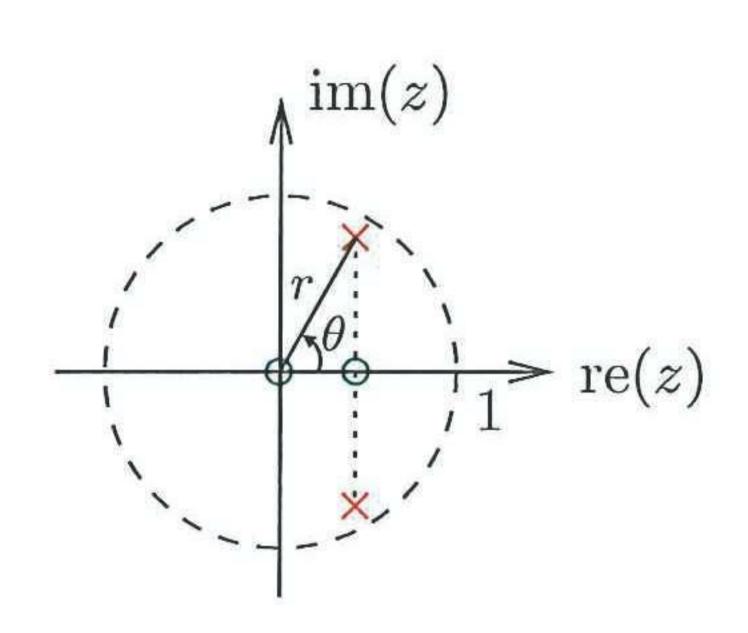


Figure 4: Pole-zero map.

- a) Determine the corresponding system function. What is the region of convergence? Is this function unique?
- b) What are the conditions for r and θ in order to have a BIBO stable system? Motivate your answer.
- c) Determine and sketch the magnitude response of the system.
- d) Compute the inverse \mathbb{Z} -transform of the system function H(z) in case the region of convergence is |z| > r.
- e) Assume the impulse response of the system is given by $h(n) = r^n \cos(n\theta)$. Just by looking to the impulse response itself, what can you say about the conditions for r and θ in order to have a BIBO stable system? How do these results relate to the ones obtained under item b)?

Consider the following (suddenly applied) input signal

$$x(n) = e^{j\frac{\pi}{4}n}u(n),$$

and assume the system is initially in rest.

f) Compute the total response of the system $y(n) = y_{\rm tr}(n) + y_{\rm ss}(n)$, where $y_{\rm tr}(n)$ and $y_{\rm ss}(n)$ denote the *transient* and *steady-state* response of the system, respectively.